

# Tailoring the dynamics of spintronic neural networks

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NEnG  
NEUROMORPHIC  
ENGINEERING GROUP



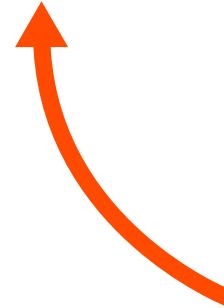
San Diego | August 18, 2024



SPIE. OPTICS+  
PHOTONICS

## Spintronic neural networks

What? Why? How?



Spintronic neural  
networks

What? Why? How?

Applications

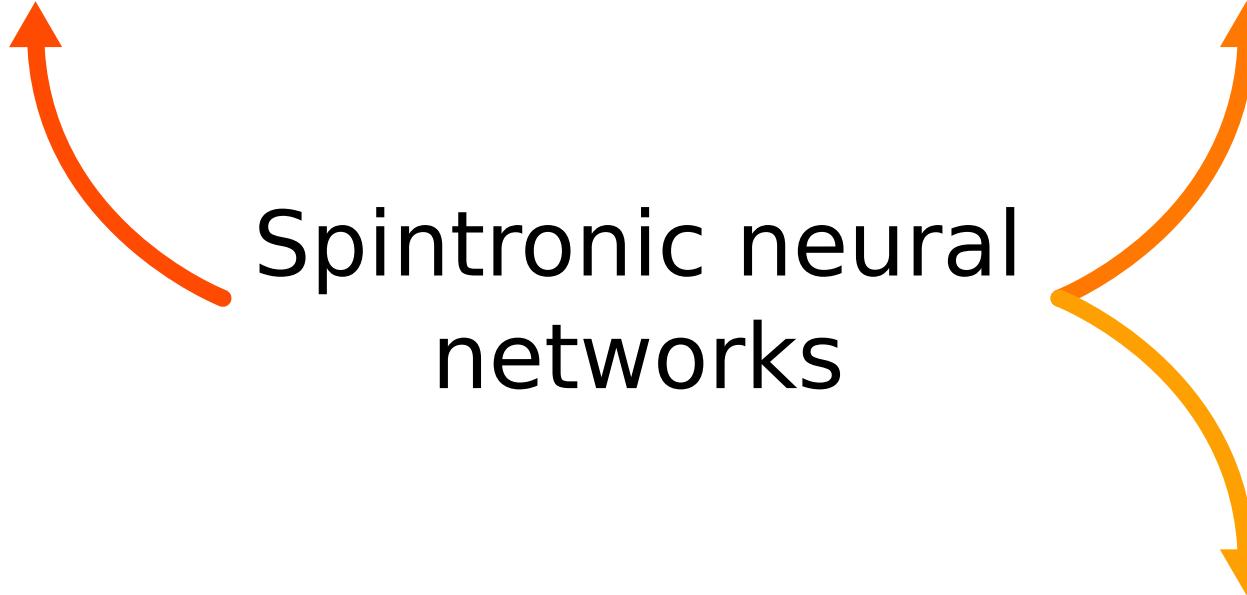
Spintronic neural  
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What? Why? How?

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Simulation &  
optimization

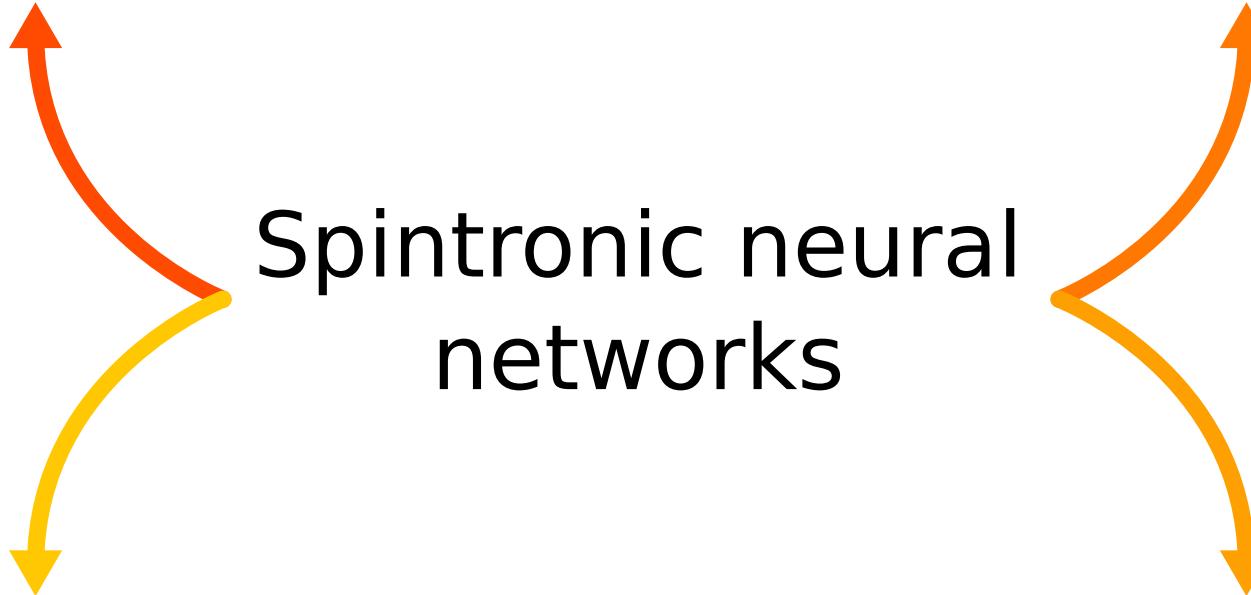
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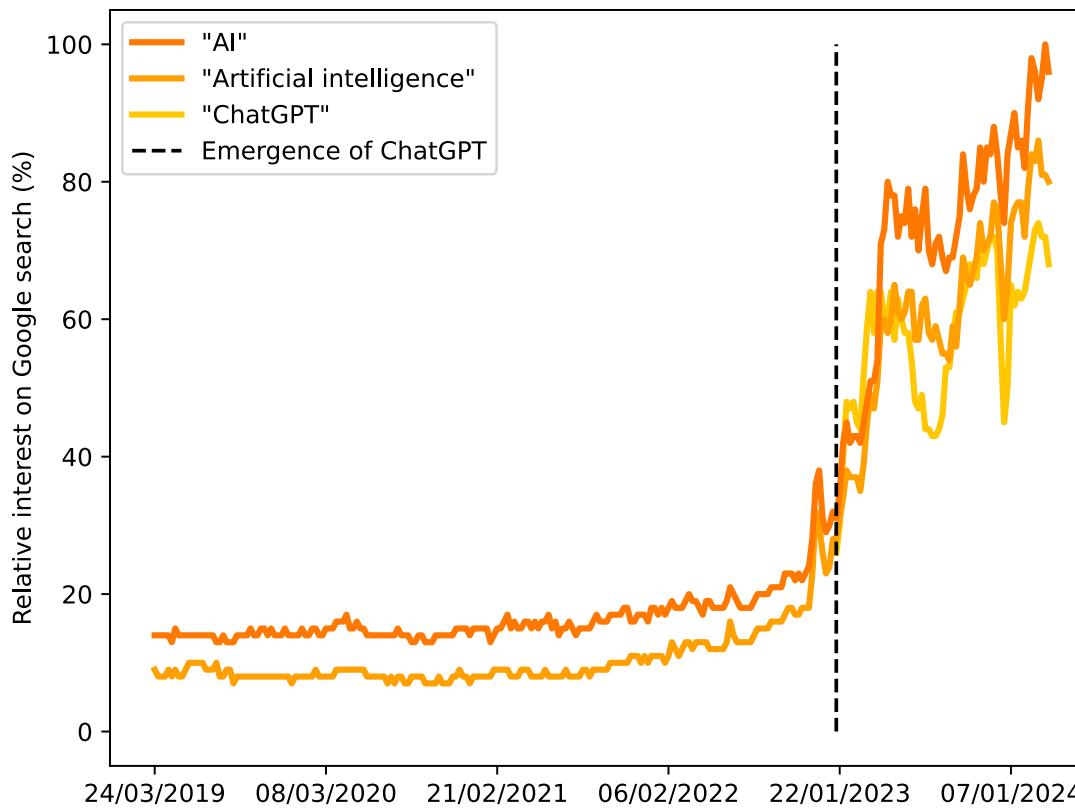
Perspectives

Simulation &  
optimization



# The artificial intelligence (AI) landscape in 2024

Unprecedented popularity and use



Google Trends (2024)

Chatbots  
Image & video generation  
Agriculture  
Healthcare  
Industry  
...

# The shadows in the AI landscape



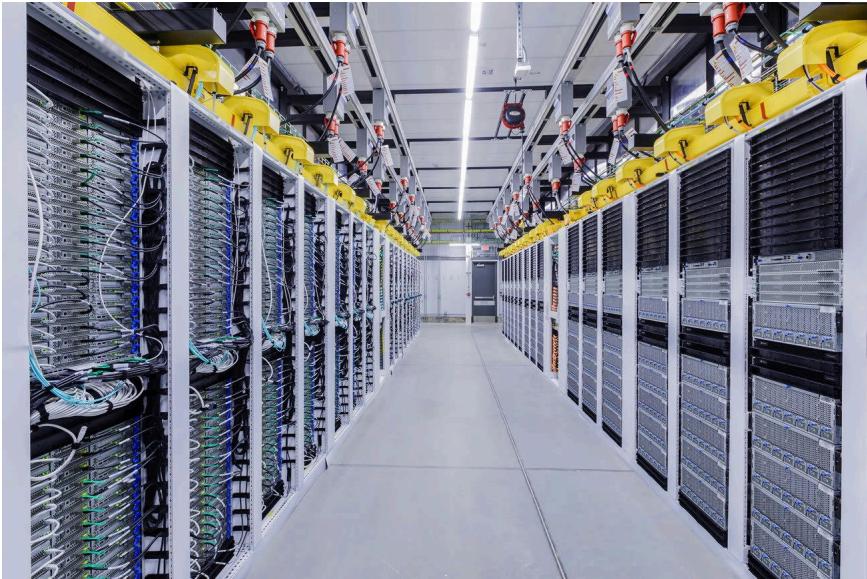
## Energy consumption

- **Training** >1300 MWH (= 130 US homes for 1 year) for GPT-3
- **Inference**: 1 image with Dall-E 3 = charging a smartphone

A. Luccioni, S. Viguier, and A. Ligozat, [arXiv preprint  
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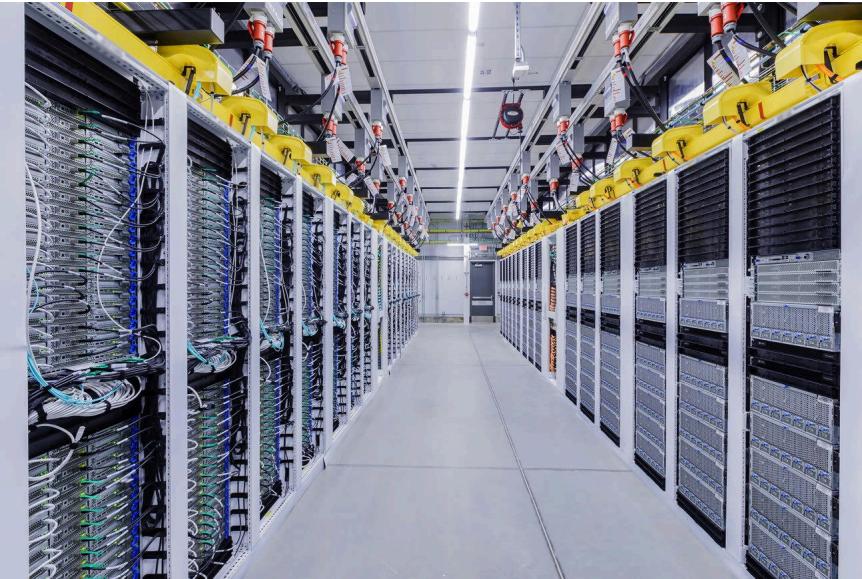
## Centralization and privacy

- Queries to **remote servers** → Internet connection
- **Proprietary servers** → data protection ?

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## Exponential development

- **Energy consumption > global production in 2040**
- IoT, monitoring in remote areas, agriculture  
→ **low connectivity and power resources**

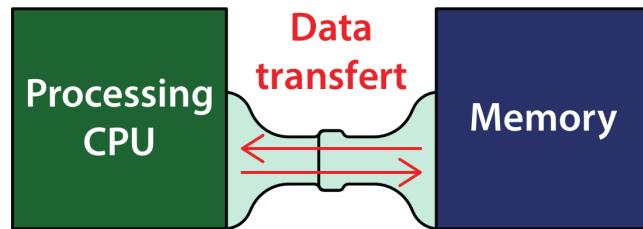
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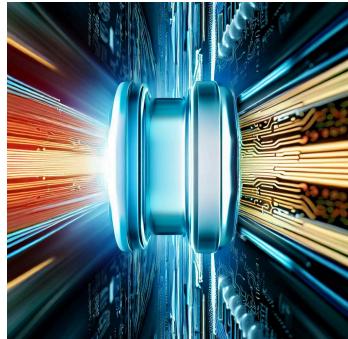
V. Sangwan, and M. Hersam, [Nature nanotechnology 15, 7](#) (2020)

# Computing beyond von Neumann

## von Neumann architecture



## Conventional AI schemes



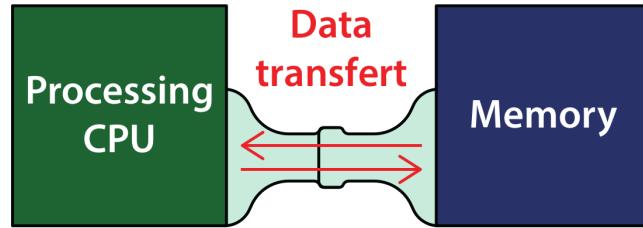
DALL·3 prompt:

*“A bottleneck representing  
limitations due to the separation  
between the CPU and the RAM”*

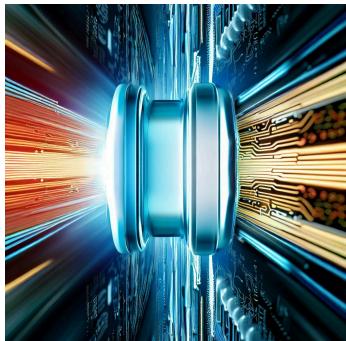
**130 kW !**

# Computing beyond von Neumann

## von Neumann architecture



## Conventional AI schemes



### DALL·3 prompt:

*“A bottleneck representing limitations due to the separation between the CPU and the RAM”*

**130 kW !**

## Energy-efficient machine learning

### Unconventional ML schemes

*Reservoir computing,  
Ising machines, spiking neural  
networks...*

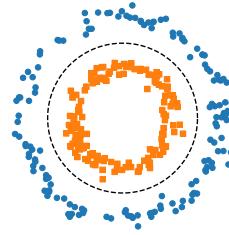
### Physical implementations

*Dynamical, nonlinear, probabilistic devices and systems*

- 1. Random nonlinear projections learning**
2. Hardware implementation using spintronic devices
3. Applications
4. High-throughput modeling of spintronic neural networks
5. Tuning and optimization
6. Towards fully spintronic networks using a hardware MAC operation

# Nonlinear random projections learning

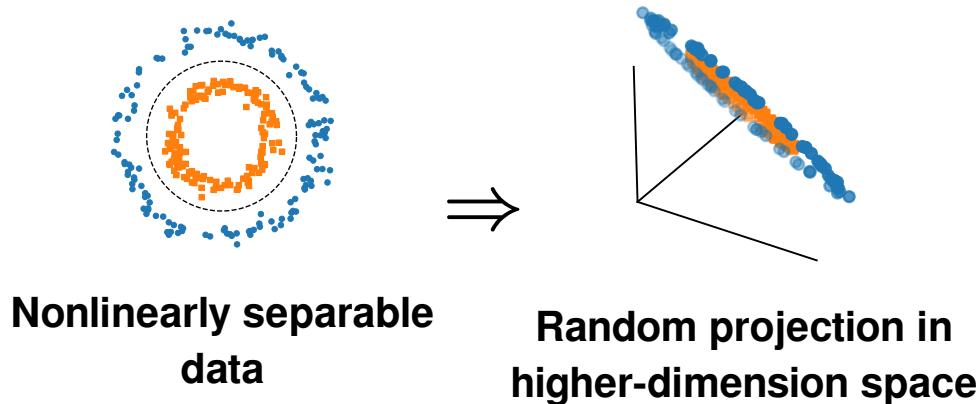
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**Nonlinearly separable  
data**

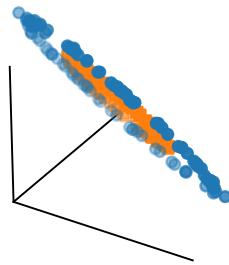
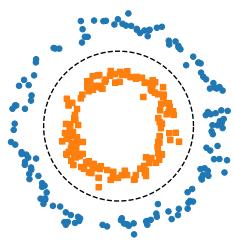
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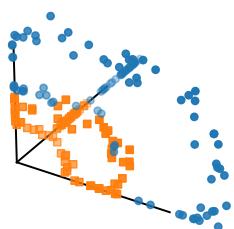
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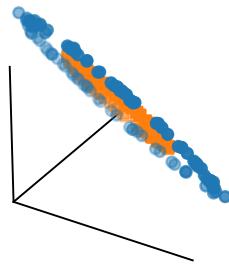
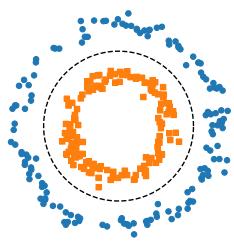
Random projection in  
higher-dimension space



Nonlinear  
transformation  
(e.g. ReLU)

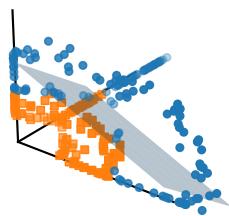
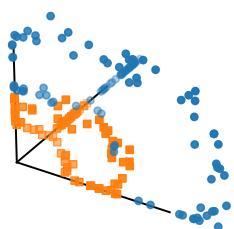
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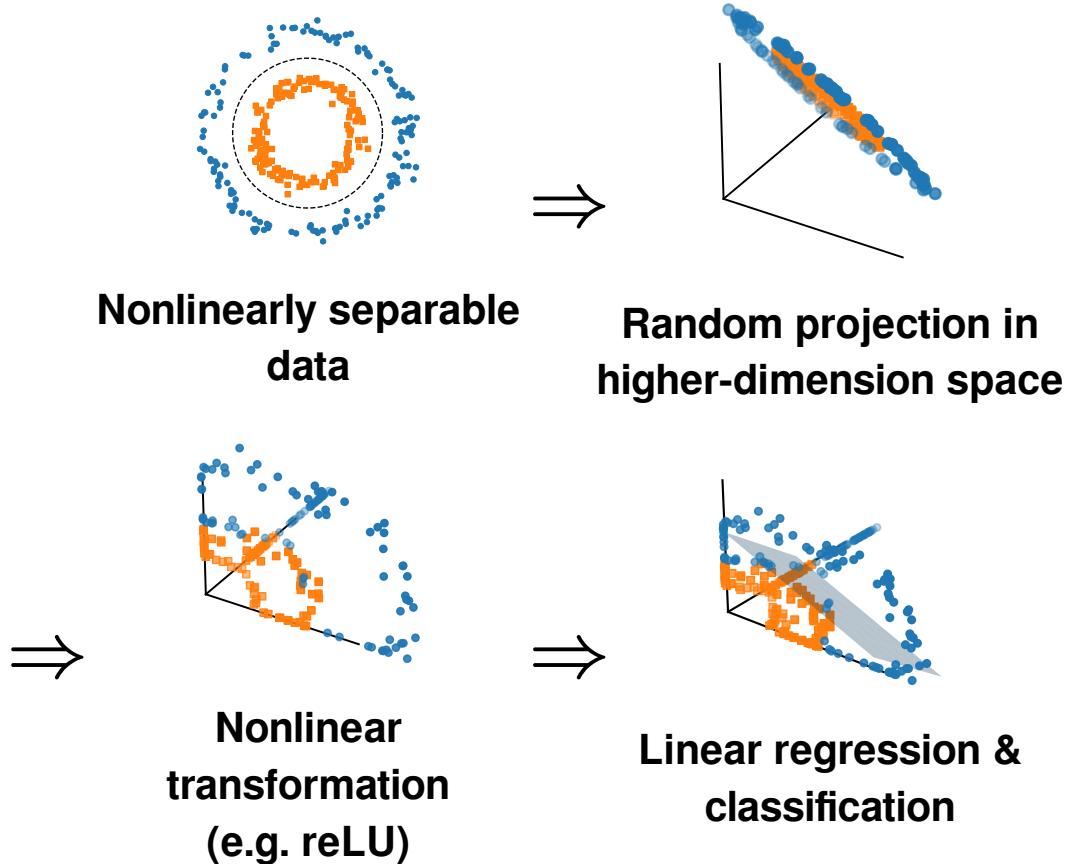


⇒  
Nonlinear  
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⇒  
Linear regression &  
classification

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# Nonlinear random projections learning



## In a nutshell

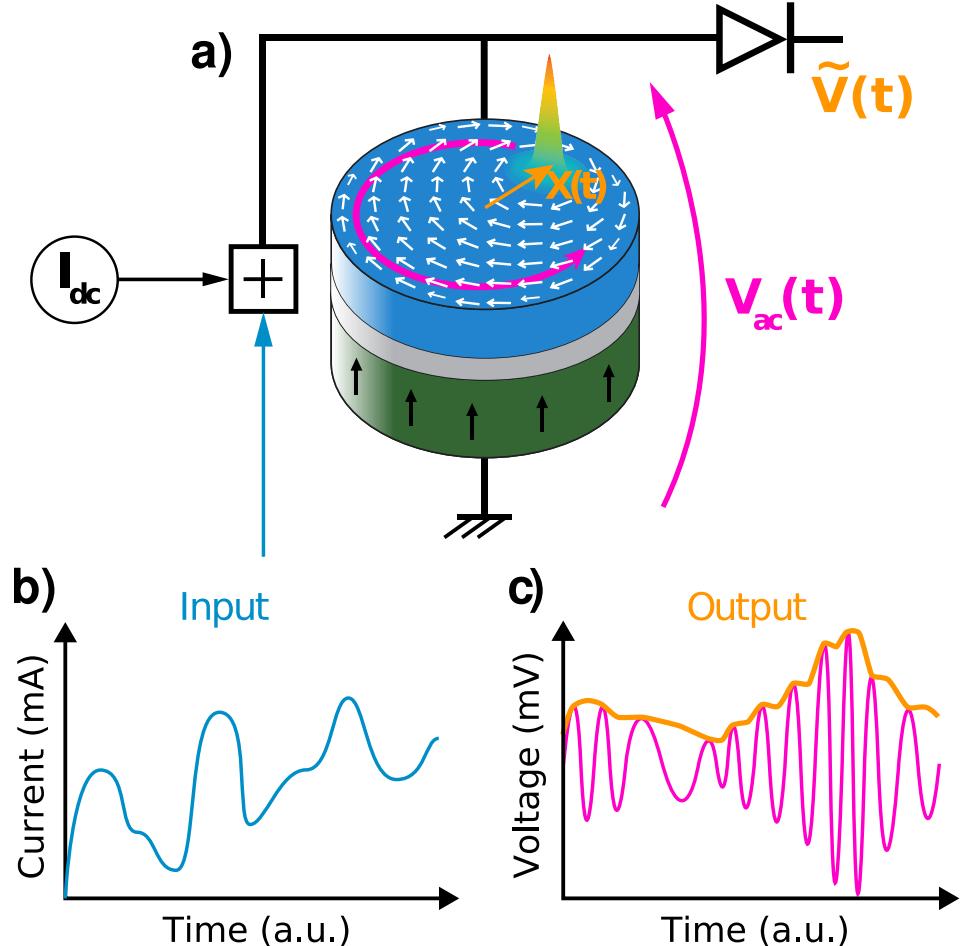
- Classification, clustering, time series prediction, ...
- Simple neural architectures
- Random and fixed hidden weights (only the **readout weights** are learned)
- Fast training (linear regression through least squares optimization)
- Global optimum is found

G. Huang, Q. Zhu, and C. Siew, *Neurocomputing* 70, 1-3 (2006)

1. Random nonlinear projections learning
- 2. Hardware implementation using spintronic devices**
3. Applications
4. High-throughput modeling of spintronic neural networks
5. Tuning and optimization
6. Towards fully spintronic networks using a hardware MAC operation

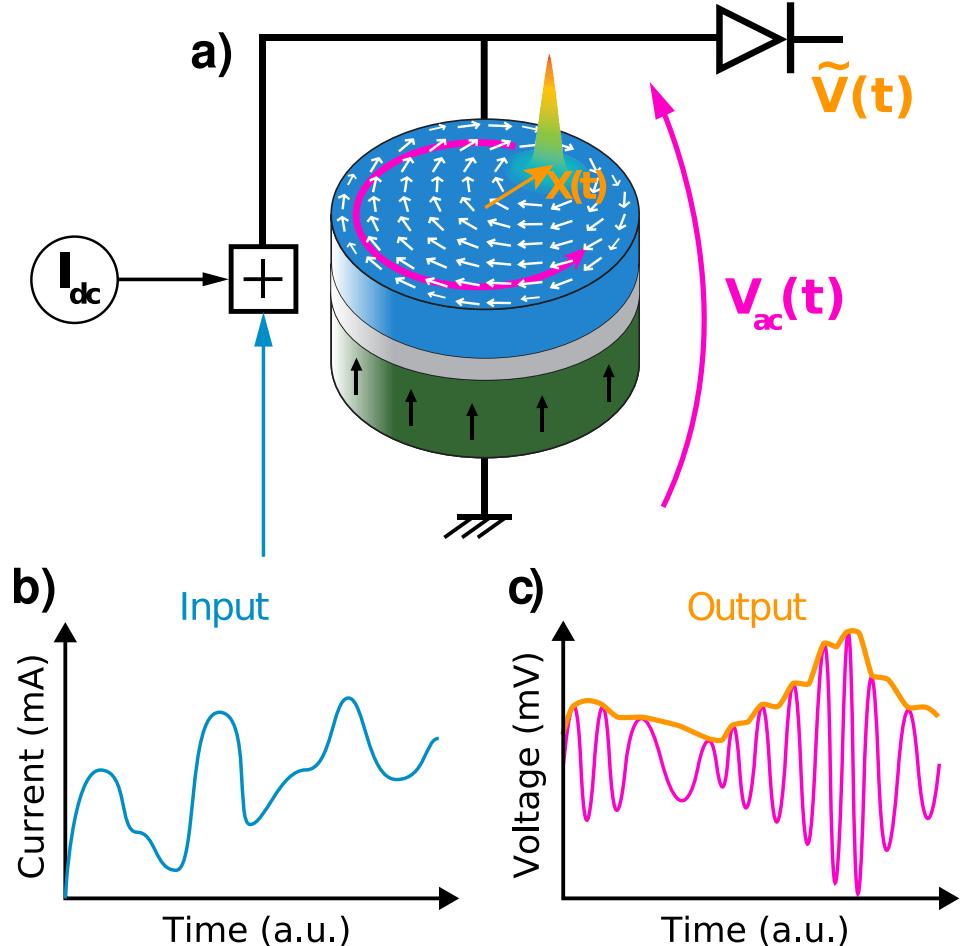
# Spin-torque vortex oscillators (STVOs)

- **Magnetic tunnel junctions (MTJs):** 3-layered magnetic nanostructures
  1. Spin polarization
  2. Spin-transfer torque (STT)
  3. Tunnel magnetoresistance (TMR)
- **Nanoscale DC to AC conversion:**
- **Versatility and integrability:**



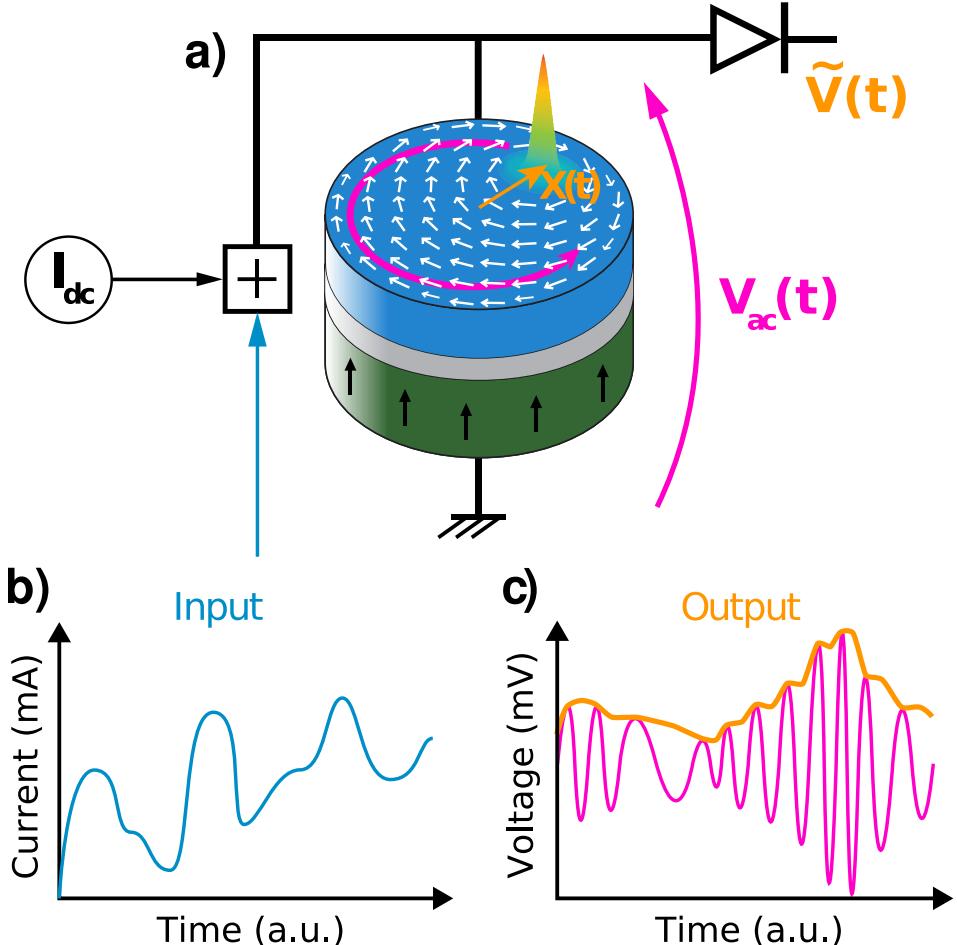
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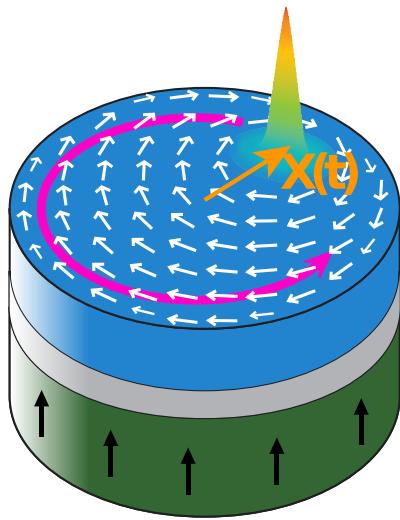


# Spin-torque vortex oscillators (STVOs)

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- **Nanoscale DC to AC conversion:** DC current injection triggers RF voltage oscillations through nonlinear magnetization dynamics.
- **Versatility and integrability:** CMOS-compatibility, fabrication and characterization well controlled (MRAM). Other physical phenomena exploitable.



# The STVO nonlinearity as an activation function

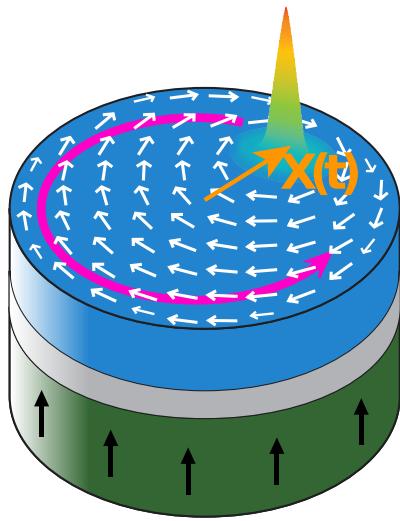


- Magnetization ground state is a *vortex*.
- STT  $\Rightarrow$  circular oscillations of the *vortex core*.
- Nonlinear voltage oscillations  $\propto$  orbit  $s(t) = \frac{X(t)}{R}$
- *Nonlinear transformation* of the input signal  
amplitude

M. Romera, P. Talatchian, S. Tsunegi, F. Abreu Araujo *et al.*, *Nature* **563**, 7730 (2018)

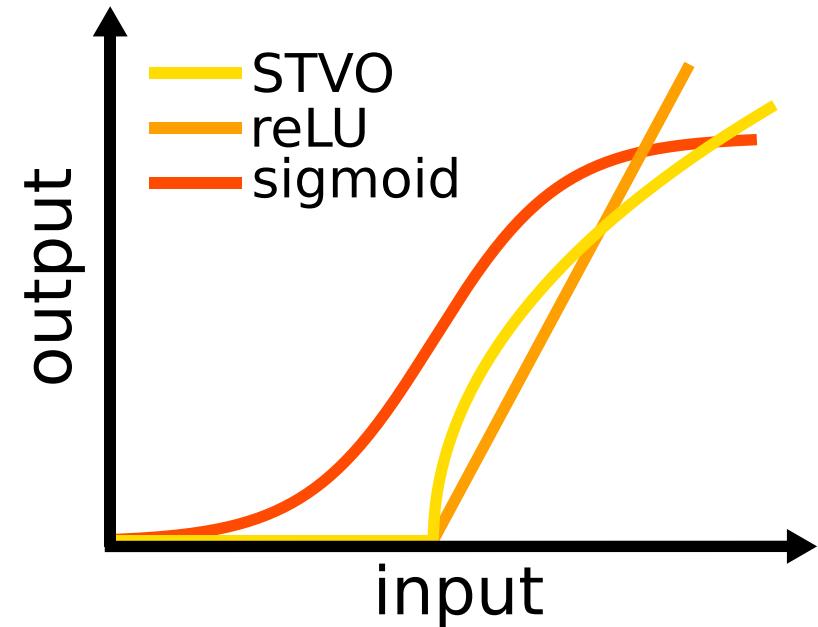
F. Abreu Araujo, M. Riou, J. Torrejon, S. Tsunegi *et al.*, *Scientific Reports* **10**, 1 (2020)

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- *Nonlinear transformation* of the input signal amplitude

Use as an activation function



... assuming an appropriate **scaling** of the input and output signals

M. Romera, P. Talatchian, S. Tsunegi, F. Abreu Araujo *et al.*, *Nature* **563**, 7730 (2018)

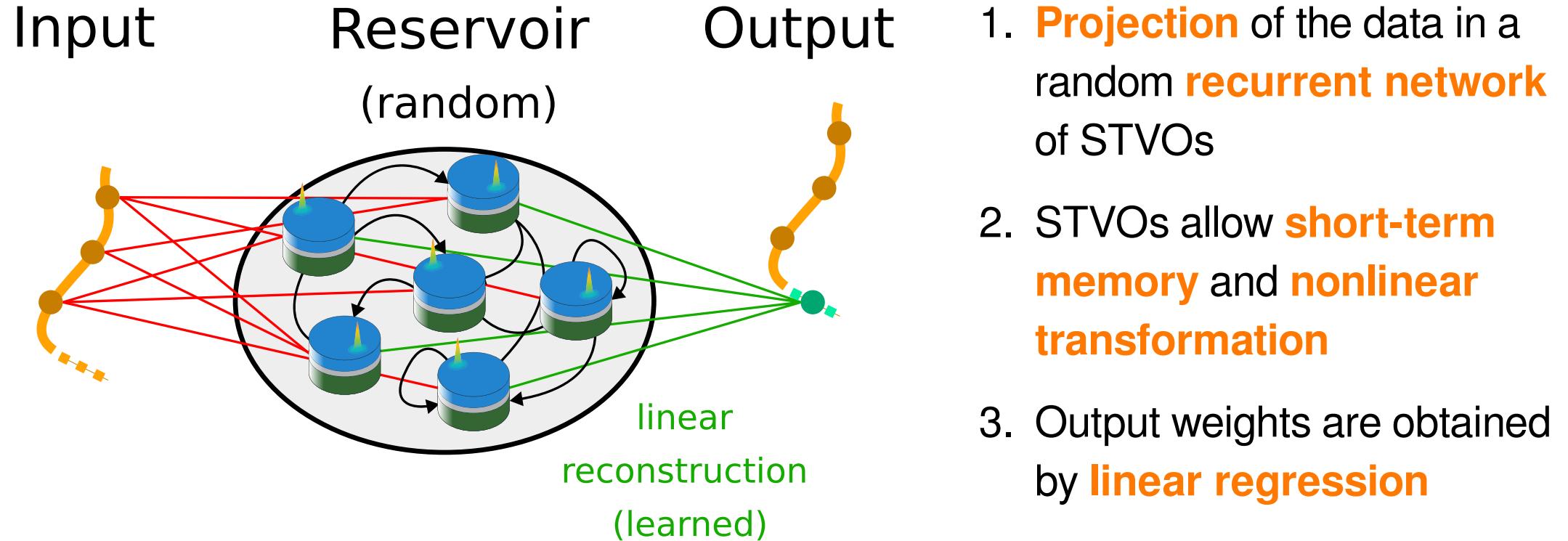
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# Timeseries forecasting using reservoir computing (RC)

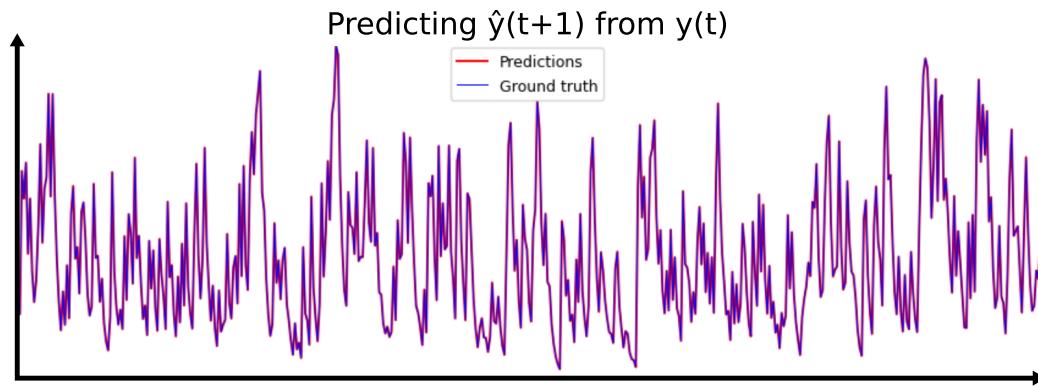


S. Shahi et al., *Machine learning with applications* 8, (2022)

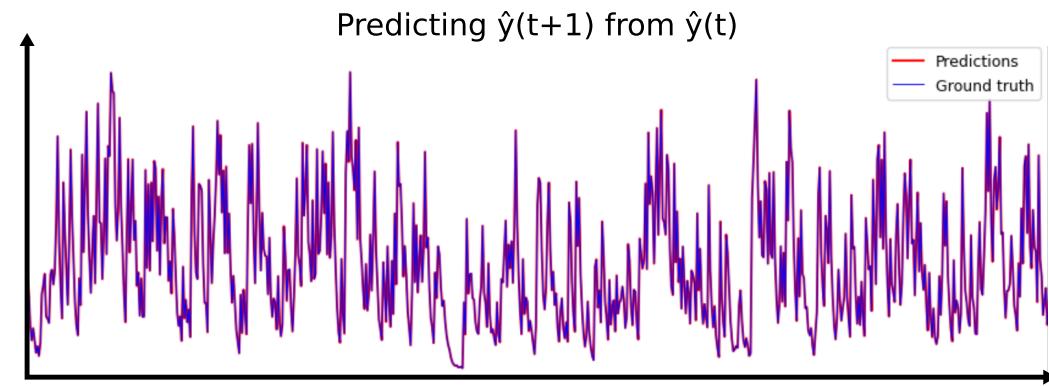
# Timeseries forecasting using reservoir computing (RC)

NARMA2: benchmark **memory capacity**, **predictive power** and **universal approximation capability**:

Predict  $y(t + 1) = \alpha y(t) + \alpha y(t)y(t - 1) + \beta u(t)$  with  $u(t)$  a noise contribution.



NMSE:  $1.36e - 04$



NMSE:  $1.84e - 04$

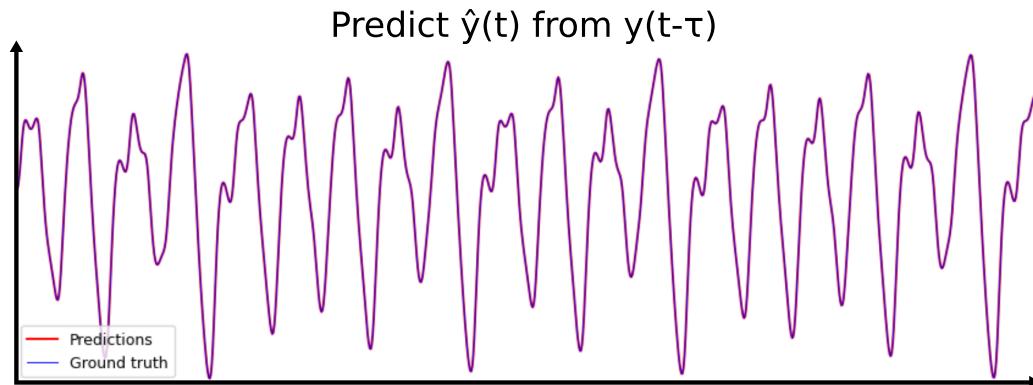
State-of-the-art performance for simulation results

Work of our MSc. student Aurian David (aurian.david@student.uclouvain.be)

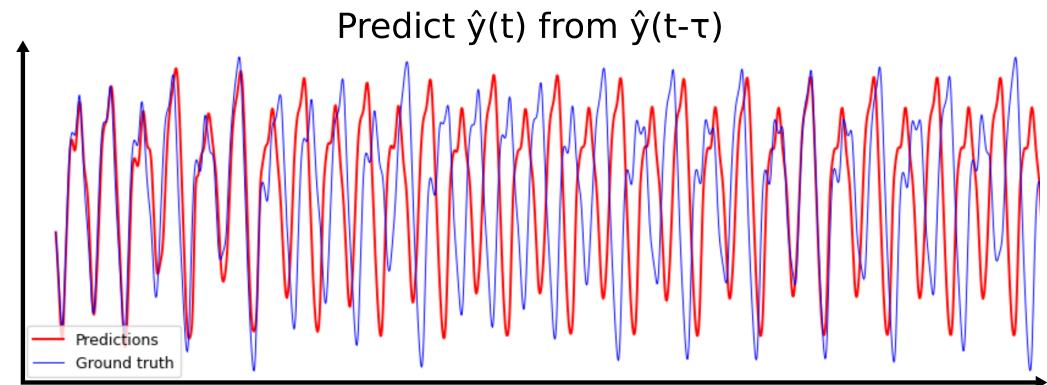
# Timeseries forecasting using reservoir computing (RC)

**Mackey-Glass chaotic timeseries prediction:** Mimicking the following chaotic system:

$$\frac{dy(t)}{dt} = \beta \frac{y(t-\tau)}{1+y(t-\tau)^n} - \gamma y(t)$$



NMSE:  $2.525e - 06$



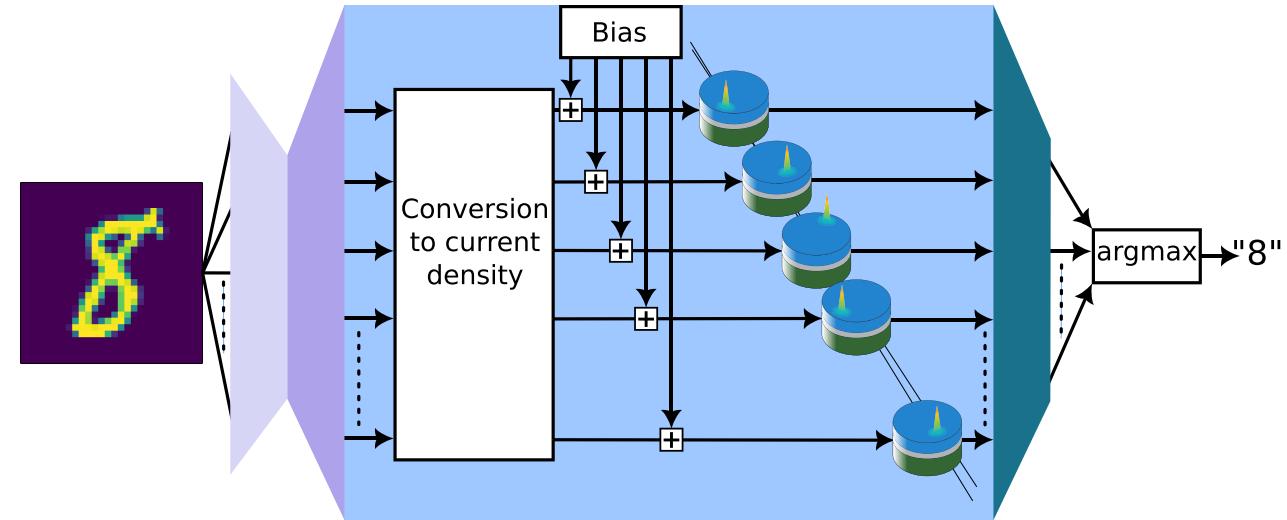
NMSE increases due to the chaotic nature of the timeseries

Work of our MSc. student Aurian David (aurian.david@student.uclouvain.be)

# Data classification using extreme learning machines (ELMs)

## Classification of static data

1. 1-hidden layer **perceptrons**
2. Train the readout weights by **linear regression**

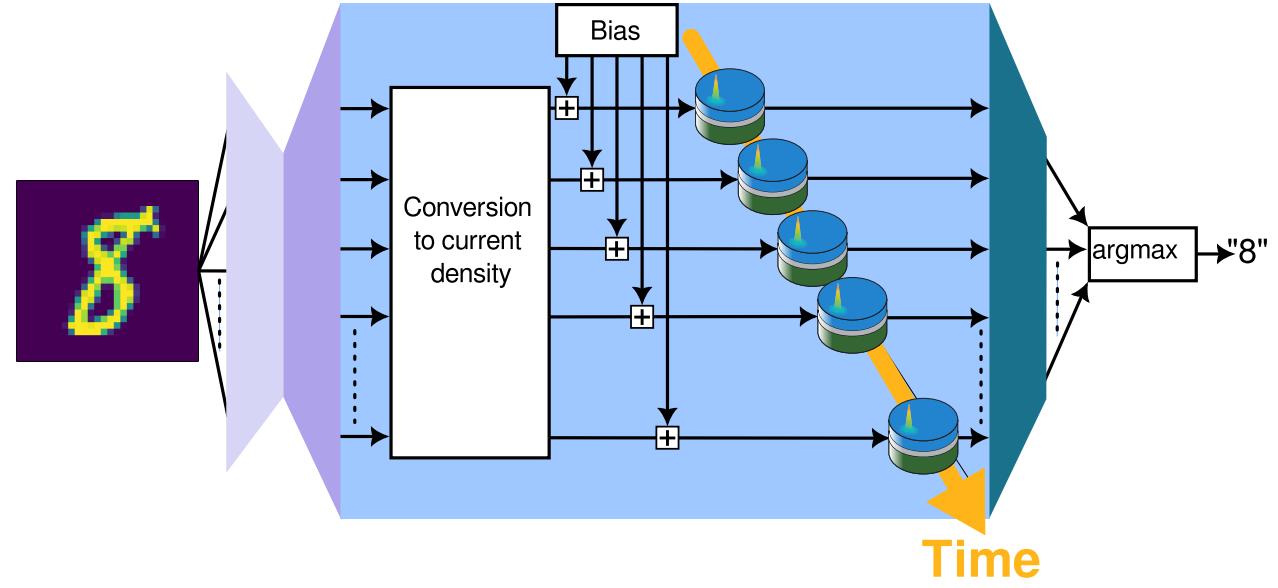


A. Moureaux, C. Chopin, S. de Wergifosse, L. Jacques, and F. Abreu Araujo, [arXiv preprint 2308.05810](https://arxiv.org/abs/2308.05810) (2023)

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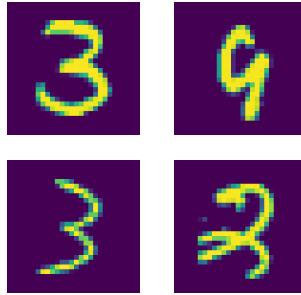
## Classification of static data

1. 1-hidden layer **perceptrons**
2. Train the readout weights by **linear regression**
3. Implementation using a single STVO by leveraging **time-multiplexing**



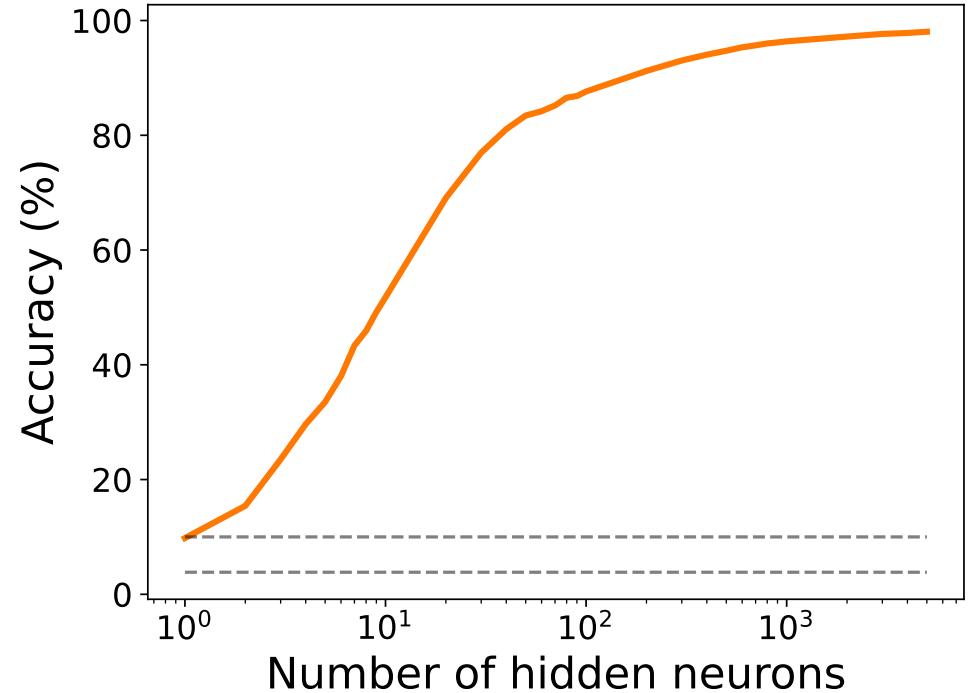
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# Image recognition



MNIST

98.1% accuracy



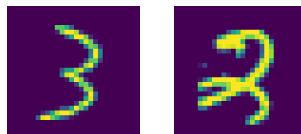
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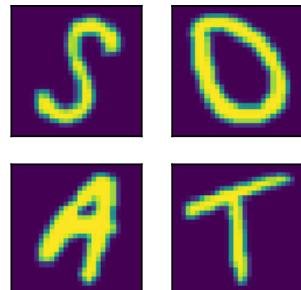
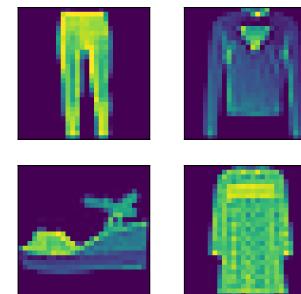
MNIST

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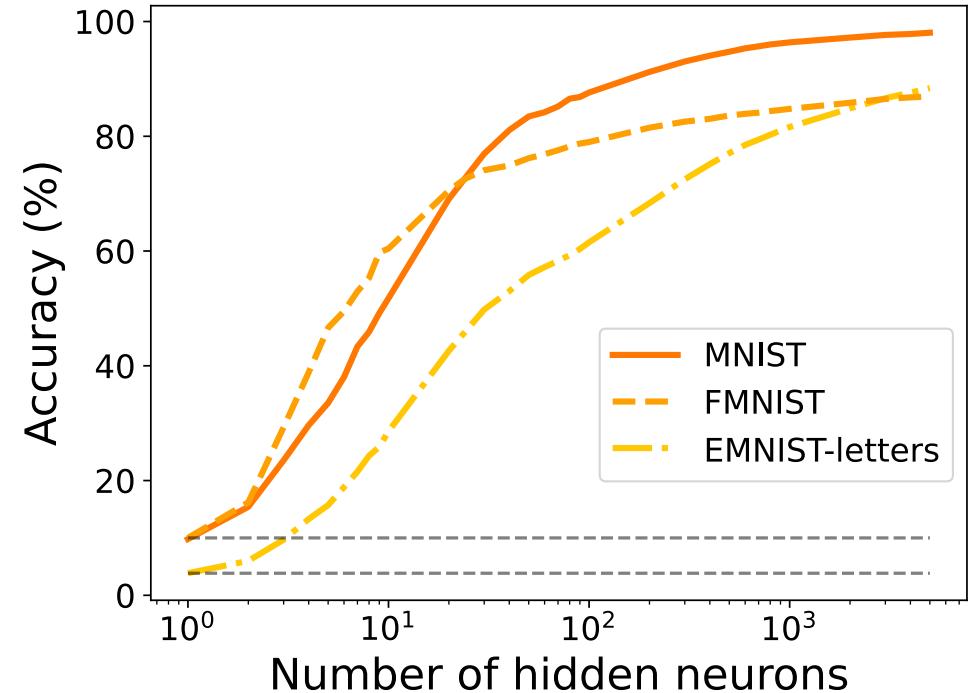
Fashion-MNIST

86.9% accuracy



Extended-MNIST-letters

88.4% accuracy



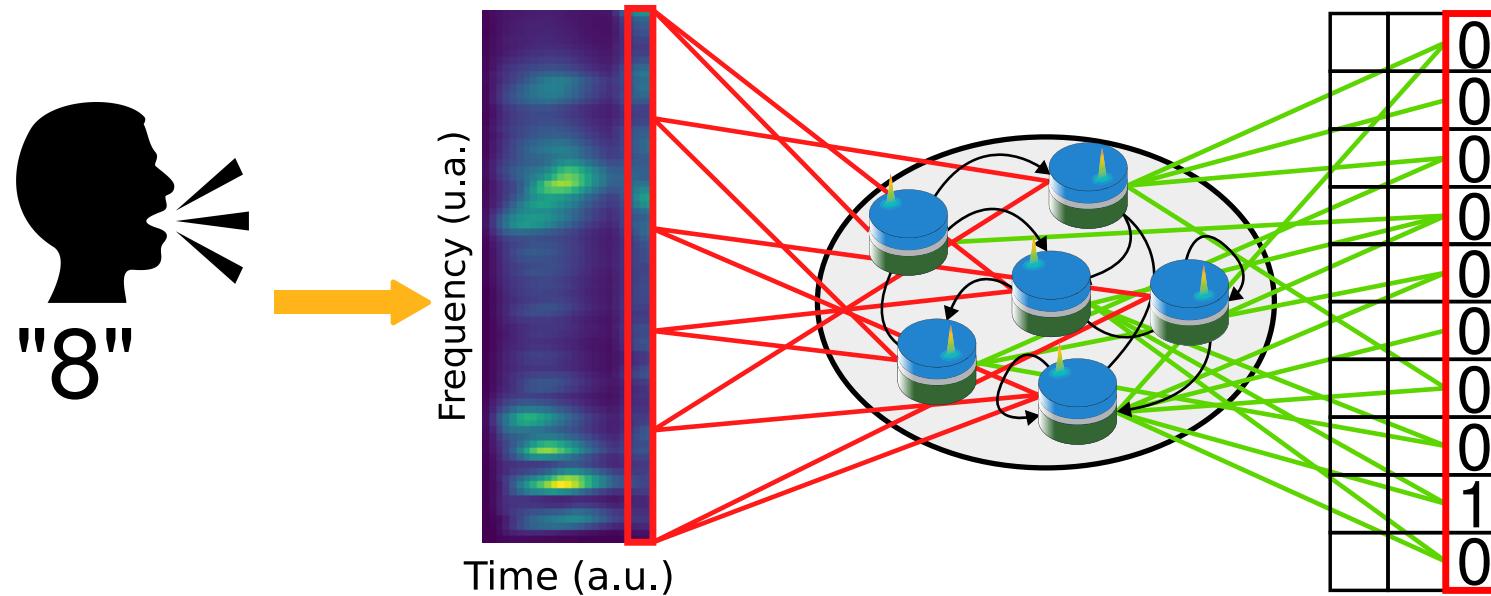
## Generalization on other datasets:

- More complex data (**FMNIST**)
- Higher number of categories (**EMNIST-letters**)

A. Moureaux, C. Chopin, S. de Wergifosse, L. Jacques, and F. Abreu Araujo, [arXiv preprint 2308.05810](https://arxiv.org/abs/2308.05810) (2023)

# An hybrid case: speech recognition

Using frequency filtering, one can **convert speech into images** containing **temporal dependency**.

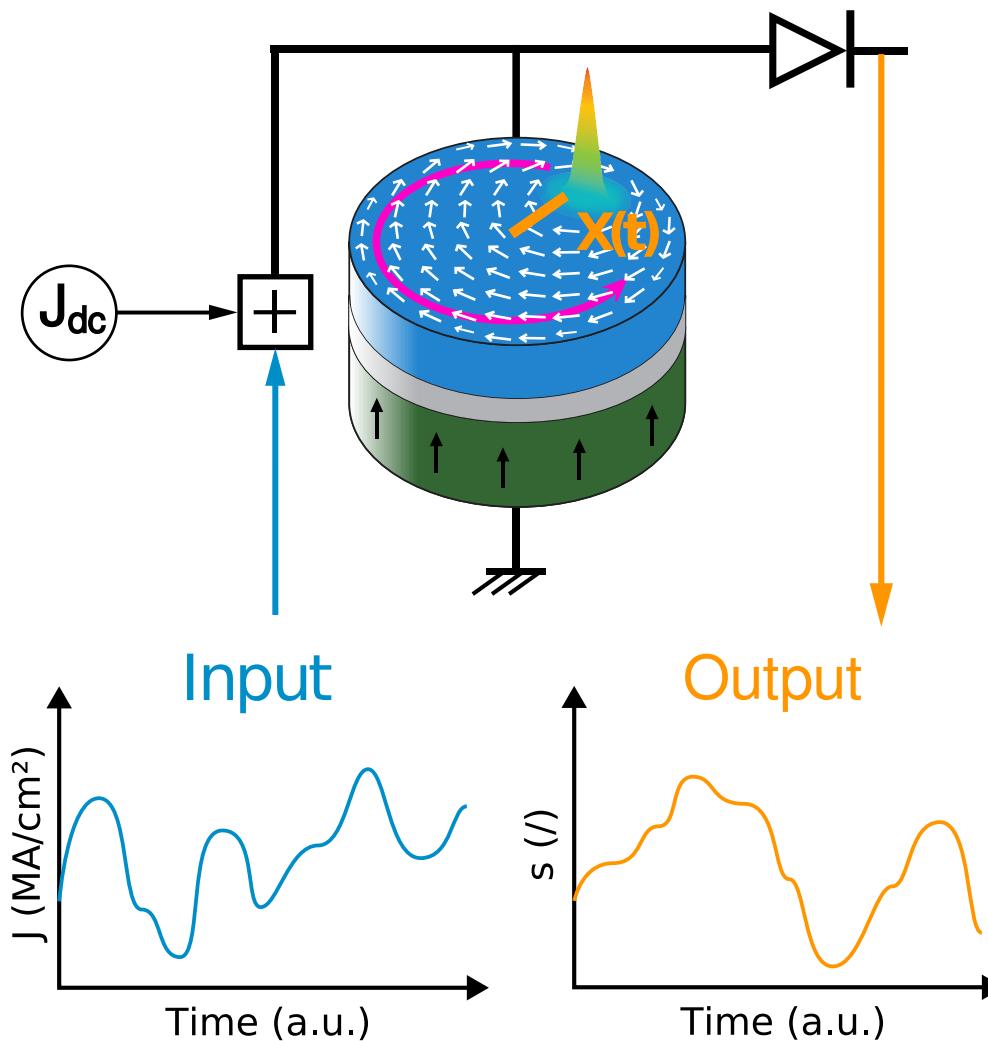


Allows classification of speech from **partial inputs**.

F. Abreu Araujo, M. Riou, J. Torrejon, S. Tsunegi, D. Querlioz *et al.*, *Scientific Reports* **10**, 1 (2020)

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# Simulating the STVO dynamics



**How to simulate the STVO nonlinearity?**

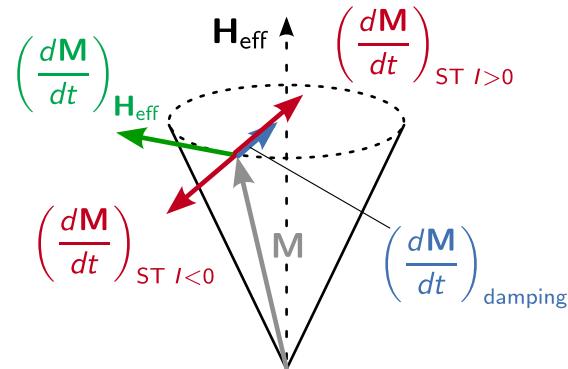
⇒ Consider  $s(J(t)) = \frac{X(J(t))}{R}$  the reduced position of the vortex core as a function of the time-varying input signal  $J(t)$ .

# Numerical and analytical frameworks

## Micromagnetic simulations (MMS)

Each STVO is divided into ~ 12800 cells

then we solve:



$$\frac{d\mathbf{M}}{dt} = -\gamma \mathbf{M} \times \mathbf{H}_{\text{eff}} + \frac{\alpha}{M_s} \mathbf{M} \times (\mathbf{M} \times \mathbf{H}_{\text{eff}}) + \Gamma_{\text{spin-torque}}$$

Accurate but very slow:

1s of dynamics: 440 years of simulation

# Numerical and analytical frameworks

## Micromagnetic simulations (MMS)

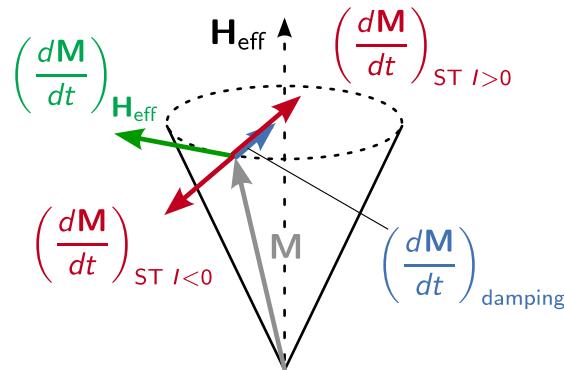
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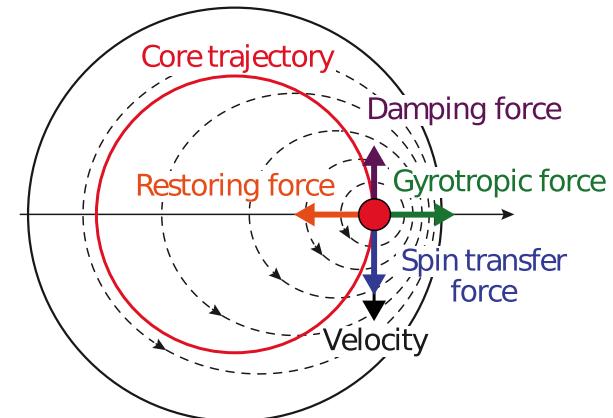
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## Thiele equation approach (TEA)

Vortex core considered as a quasi-particle in a balance of forces



Vortex core motion is described by:

$$G(\mathbf{e}_z \times \dot{\mathbf{x}}) + D\dot{\mathbf{x}} = \frac{\partial \mathbf{W}}{\partial \mathbf{x}} + \mathbf{F}^{\text{ST}} \quad \text{and} \quad \begin{pmatrix} \dot{x} \\ \dot{y} \end{pmatrix} = \begin{pmatrix} \Gamma & -\omega \\ \omega & \Gamma \end{pmatrix} \cdot \begin{pmatrix} x \\ y \end{pmatrix}$$

Fast but inaccurate

# The data-driven Thiele equation approach (DD-TEA)

**MMS + TEA**

Fit the  $\Gamma$  and  $\omega$  parameters from the **TEA**  
using **MMS** results.

- ⇒ Renders the quantitative accuracy lacking in the **TEA framework**.
- ⇒  $2.4G\times$  faster than **MMS**.

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	MMS	TEA	DD-TEA
Accuracy	●	●	●
Speed	●	●	●
Neuromorphic spintronics	🔒	🔒	🔓

F. Abreu Araujo, C. Chopin, and S. de Wergifosse, [arXiv preprint 2206.13596](https://arxiv.org/abs/2206.13596) (2022)

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	MMS	TEA	DD-TEA
Accuracy	●	●	●
Speed	●	●	●
Neuromorphic spintronics	🔒	🔒	🔓

## What's next ?

1. Use the **DD-TEA** model to simulate the vortex core trajectory under a **given input signal**.
2. Simulate **STVO-based computing architectures**.
3. **Assess the influence of operating parameters and seek optimization.**

1. Random nonlinear projections learning
2. Hardware implementation using spintronic devices
3. Applications
4. High-throughput modeling of spintronic neural networks
- 5. Tuning and optimization**
6. Towards fully spintronic networks using a hardware MAC operation

**Physical parameters**  
affecting the STVO dynamics.

- ▶ **Peak-to-peak amplitude** of the input signal (mean = 0)
- ▶ **Bias** of the input signal
- ▶ **Sampling rate** of the input signal
- ▶ External magnetic field, temperature, noise, ...

# Parameters of interest

## Physical parameters

affecting the STVO dynamics.

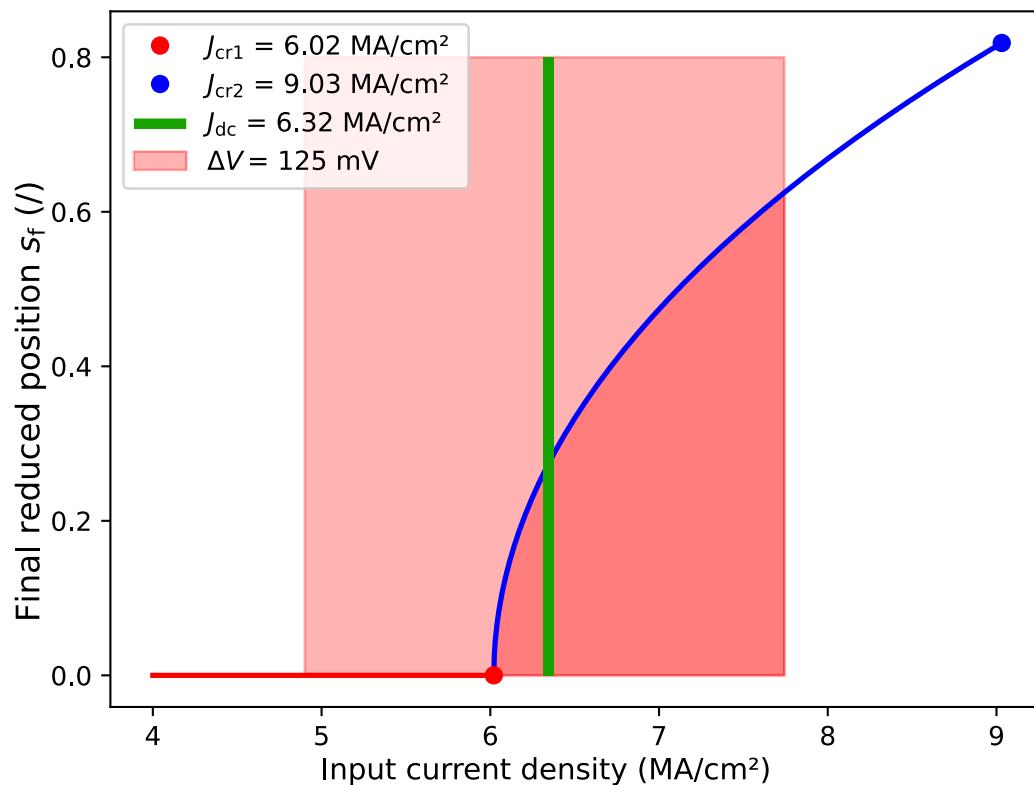
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- ▶ **Sampling rate** of the input signal
- ▶ External magnetic field, temperature, noise, ...

## Hyperparameters

affecting the architecture of the network

- ▶ Number of **nonlinear units** ( $\# \text{neurons} \propto \# \text{parameters}$ )
- ▶ **Input weights** (fixed randomly)
- ▶ **Reservoir computing**: Connectivity matrix, spectral radius, ...

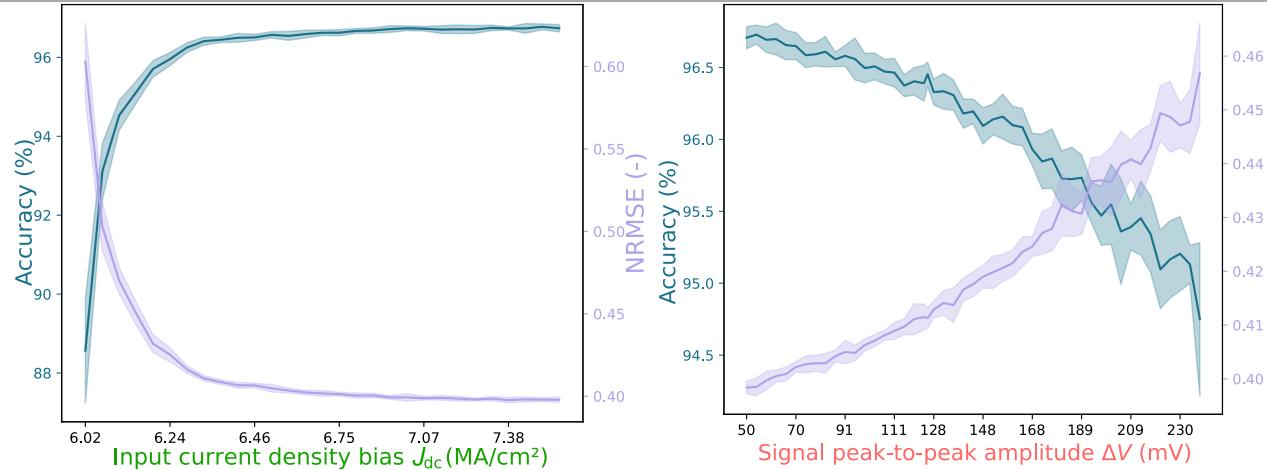
# Physical parameters



- Input signal distributed around the bias  $J_{dc}$
- Below  $J_{cr1}$ : no oscillations/damping regime
- Above  $J_{cr2}$ : vortex is expelled (hard limit)

- Bias current density  $J_{dc}$ : controls the position of the input signal between the two critical values  $J_{cr1}$  and  $J_{cr2}$ .  
⇒ which part of the dynamics is sounded by the STVO.
- The amplitude of the input signal defines the width of the range of the dynamics sounded by the STVO.  
⇒ “richness” of the transformation.

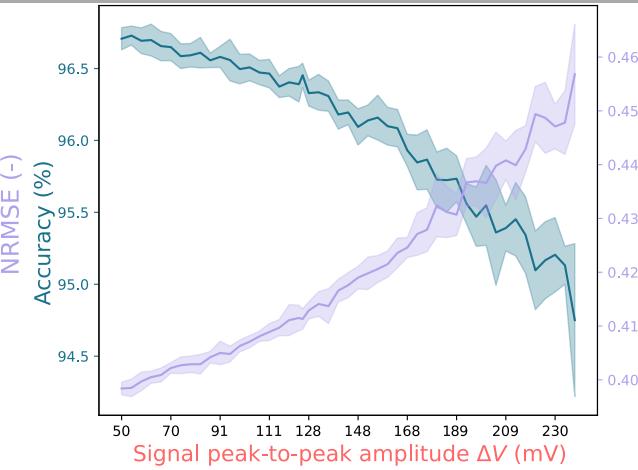
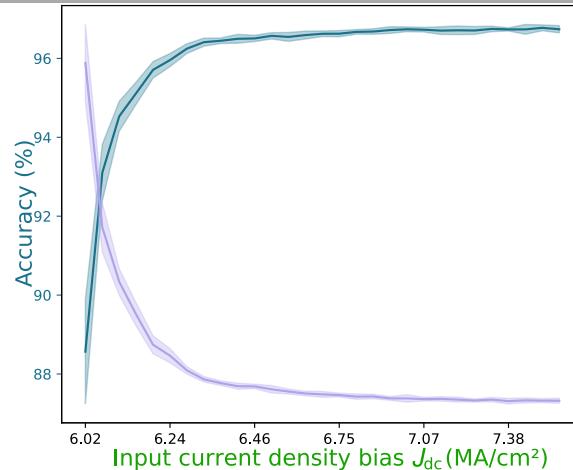
# Image recognition (MNIST handwritten digits)



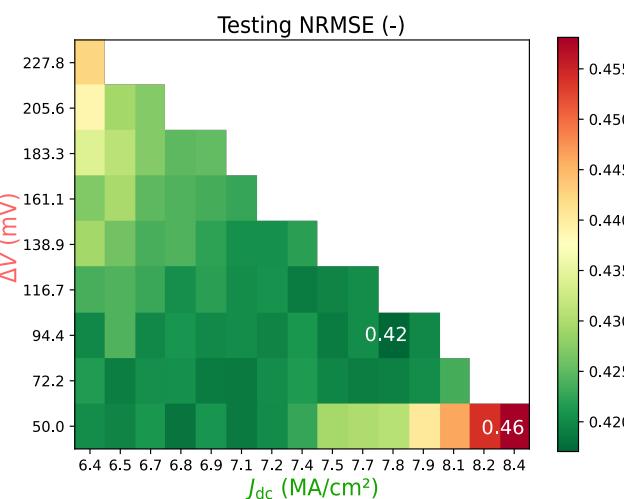
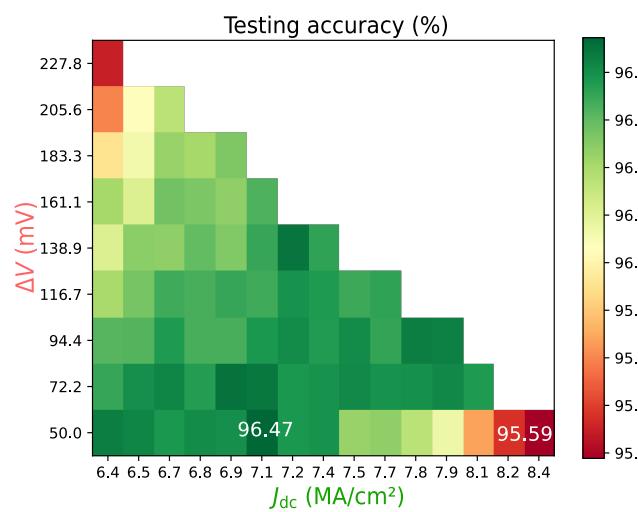
► Better performance (higher accuracy and lower error) at **high bias current density** and **low signal amplitude**.

A. Moureaux, C. Chopin, S. de Wergifosse, L. Jacques, and F. Abreu Araujo, [arXiv preprint 2308.05810](https://arxiv.org/abs/2308.05810) (2023)

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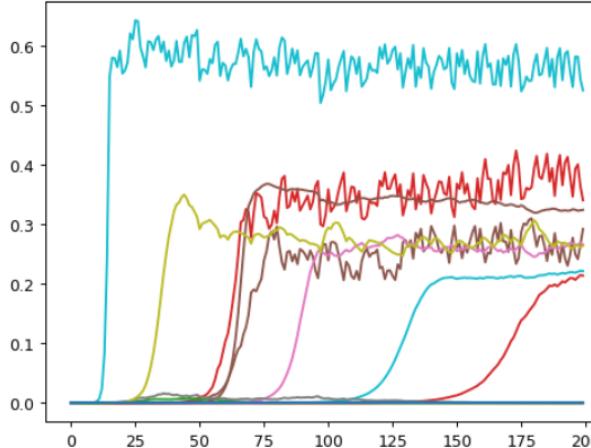
► However, interplay between these two parameters !  
⇒ Need **joint grid search** for efficient optimization.

A. Moureaux, C. Chopin, S. de Wergifosse, L. Jacques, and F. Abreu Araujo, [arXiv preprint 2308.05810](https://arxiv.org/abs/2308.05810) (2023)

# Timeseries forecasting (NARMA2)

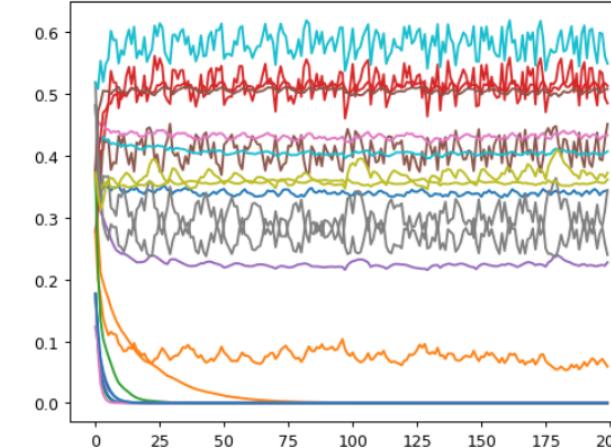
## Influence of the bias current density $J_{dc}$

Activations  $\mathbf{x}(n)$  from Reservoir Neurons ID 0 to 20 for 200 time steps



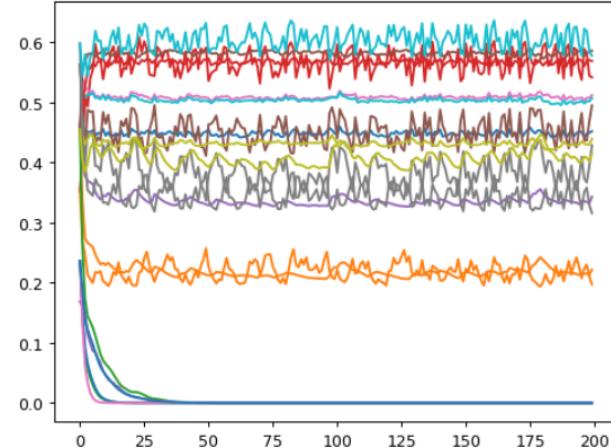
$$J_{dc}/J_{cr1} = 1$$

Activations  $\mathbf{x}(n)$  from Reservoir Neurons ID 0 to 20 for 200 time steps



$$J_{dc}/J_{cr1} = 1.1$$

Activations  $\mathbf{x}(n)$  from Reservoir Neurons ID 0 to 20 for 200 time steps



$$J_{dc}/J_{cr1} = 1.15$$

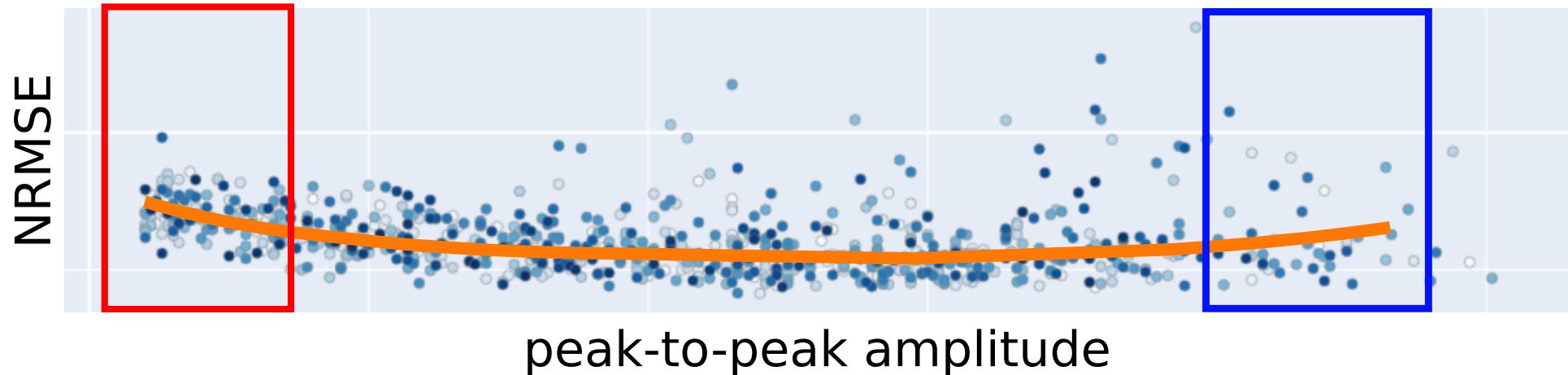
⇒ Lower  $J_{dc}$  values tend to delay the triggering of the oscillations.

⇒ Higher  $J_{dc}$  values increase the accuracy reached for the NARMA2 forecasting.

Work of our MSc. student Aurian David (aurian.david@student.uclouvain.be)

# Timeseries forecasting (NARMA2)

## Influence of the peak-to-peak amplitude of the input signal

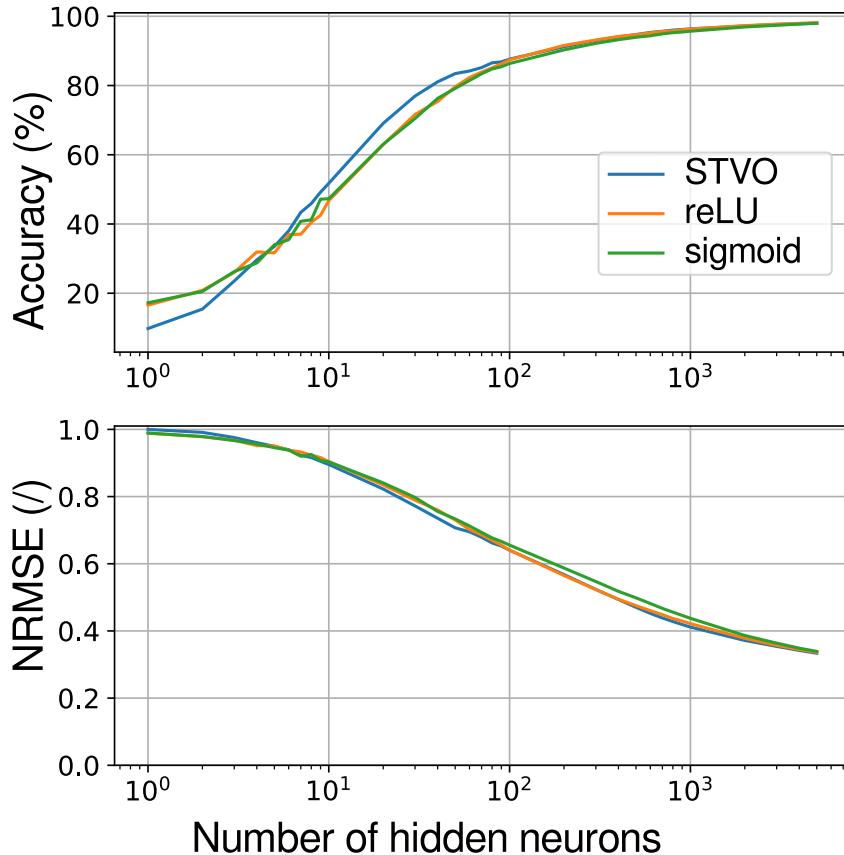


- ▶ At **small peak-to-peak amplitude**, the transformation becomes linear  $\Rightarrow$  prediction error  $\nearrow$ .
- ▶ At **high peak-to-peak amplitude**, the variance of the output  $\nearrow \Rightarrow$  prediction error  $\nearrow$ .

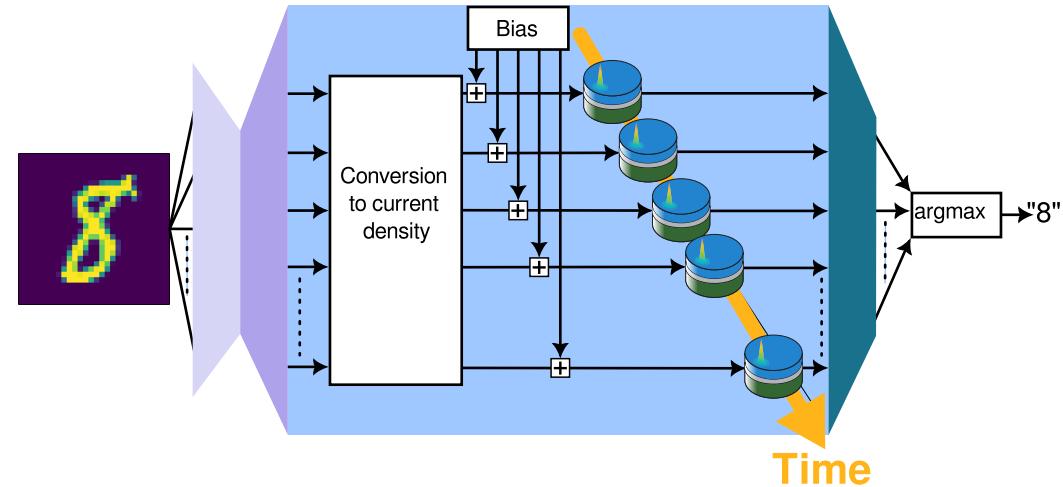
Work of our MSc. student Aurian David (aurian.david@student.uclouvain.be)

# Hyperparameters

⇒ Assess the influence of architecture-related parameters



EX: MNIST handwritten digits images recognition

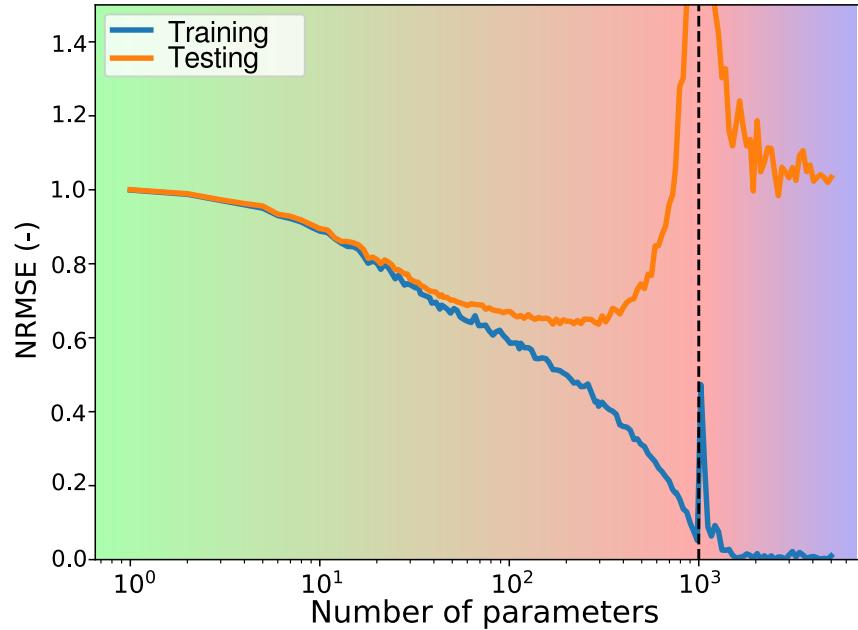


Influence of **#parameters** and comparison to conventional nonlinear functions.

A. Moureaux, C. Chopin, S. de Wergifosse, L. Jacques, and F. Abreu Araujo, [arXiv preprint 2308.05810](https://arxiv.org/abs/2308.05810) (2023)

# Hyperparameters

⇒ Assess the influence of architecture-related parameters



**Double-descent phenomenon:**

2 successive decreases of the training NRMSE when the complexity of the network ↗

► **Underparametrized regime:**

NRMSE ↓ a first time when complexity ↗ as the variance of the model increases

► **Interpolation regime:**

NRMSE ↑ due to the maximal variance of the model (*overfitting*)

► **Overparametrized regime:**

NRMSE ↓ a second time due to the decrease of the model's variance (intrinsic regularization).  
(*undergoing work*)

P. Nakkiran, G. Kaplun, Y. Bansal, T. Yang, B. Barak et al., [arXiv preprint 1912.02292](https://arxiv.org/abs/1912.02292) (2019)

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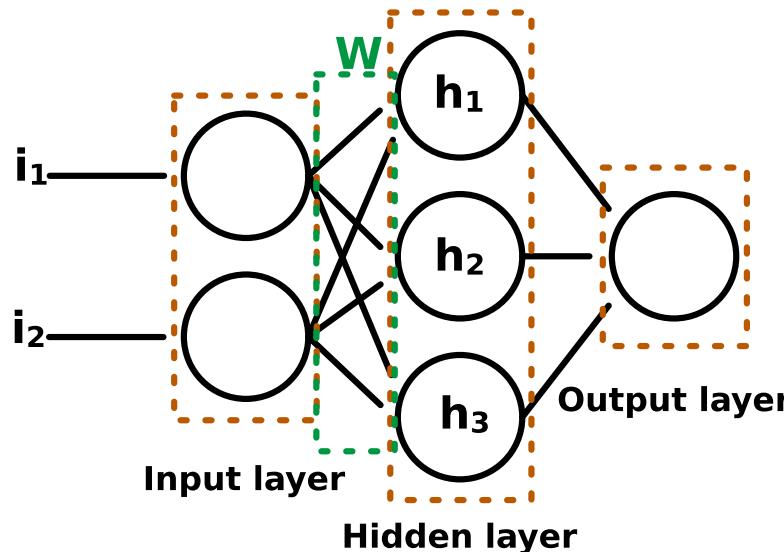
## Maths in neural networks:

### Nonlinear transformations

⇒ Data processing inside the nodes

### Multiply-and-accumulate (MAC) operation

⇒ Propagate the information in the network



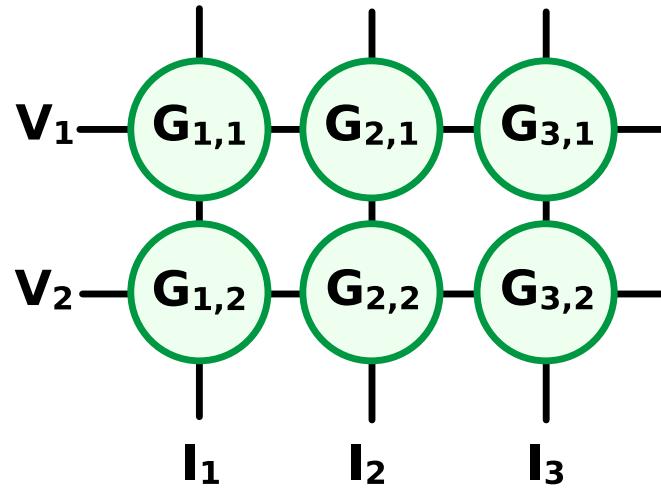
MAC operation: weighted sum for the input of a given node:

$$h_k = \sigma\left(\sum_j w_{jk} i_j\right)$$

$$\underline{h} = \sigma(\underline{w} \cdot \underline{i})$$

# Implement the MAC operation in hardware

**In-memory computing:** perform the MAC operation in dedicated hardware where the information is already stored.



**Weights** are stored as conductance states  $G_{ij}$  in separate cells.

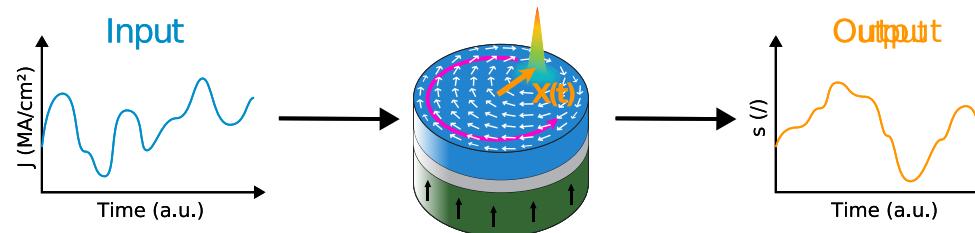
S. Jung, H. Lee *et al.*, *Nature* 601, 7892 (2022)

1. **Input** is encoded as a voltage vector  $\underline{V}$
2. **Multiplication** in each cell through Ohm's law:  $I_{ij} = G_{ij} V_j$
3. **Accumulation** through Kirchhoff's law:

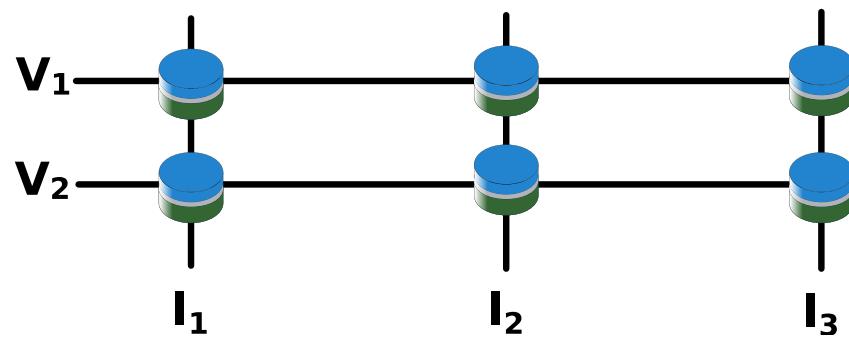
$$I_i = \sum_j I_{ij}$$
$$\underline{I} = \underline{G} \cdot \underline{V}$$

**MTJs can store distinct conductance states !**

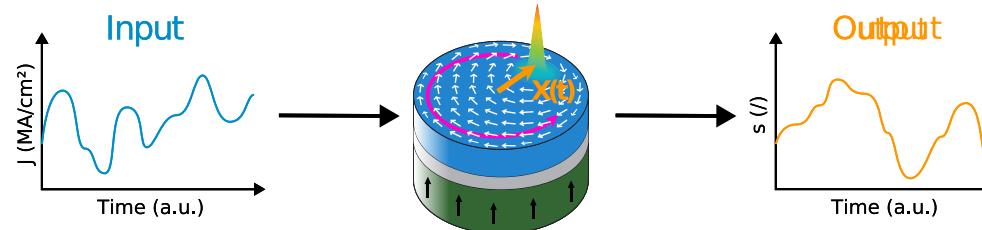
## MTJs for nonlinear transformations:



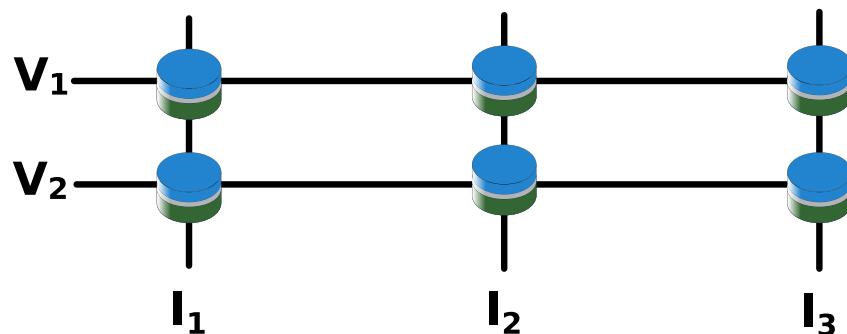
## MTJs for MAC operation:



## MTJs for nonlinear transformations:



## MTJs for MAC operation:



## MTJ-based coprocessor

- ▶ Offline training and scaling through simulation
- ▶ Low-power and fast inference on the chip
- ▶ Versatility and adaptability: signal forecasting, data classification, clustering, ...

# Take-home message

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MTJs can be used as **nonlinear units** in hardware intelligent computing systems for **timeseries forecasting** (RC) and **image classification** (ELM) at low power.

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This allows to tune **physical parameters** and optimize the performance of said networks, as well as investigating the influence of **hyperparameters**.

# Take-home message

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MTJs can be used as **nonlinear units** in hardware intelligent computing systems for **timeseries forecasting** (RC) and **image classification** (ELM) at low power.

A **data-driven approach** can be used to perform **high-throughput simulations** of entier STVO-based neural networks.

This allows to tune **physical parameters** and optimize the performance of said networks, as well as investigating the influence of **hyperparameters**.

MTJs can also store distinct conductance states. This can be leveraged to implement a **hardware MAC operation**, the other type of computation involved in neural networks.

# Acknowledgments

The Neuromorphic Engineering group @ UCLouvain, Belgium



Prof. Flávio ABREU ARAUJO  
Group leader



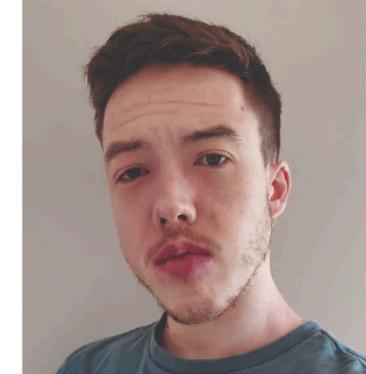
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SANTA CLARA GOMES  
Post-doctoral researcher  
(currently at INESC-MN)



Simon DE WERGIFOSSE  
Doctoral researcher



Anatole MOUREAUX  
Doctoral researcher

